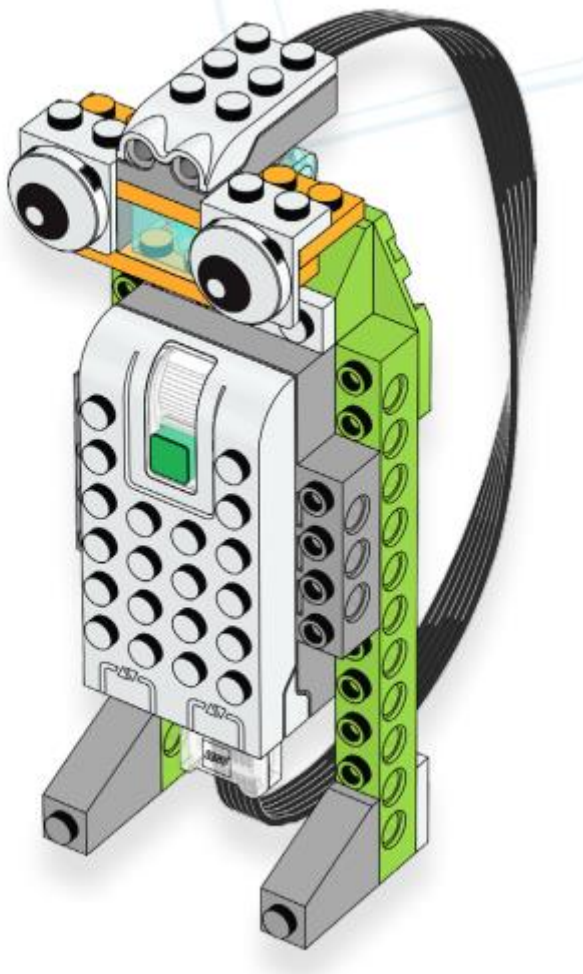
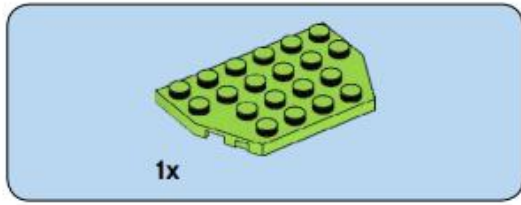


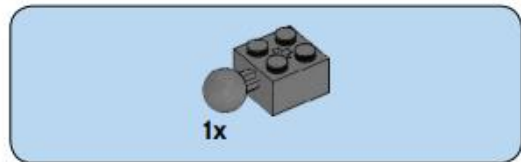
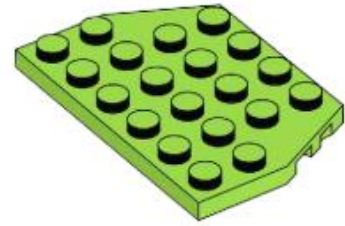
## Capítulo 4 (Spy Robot) Robot espía



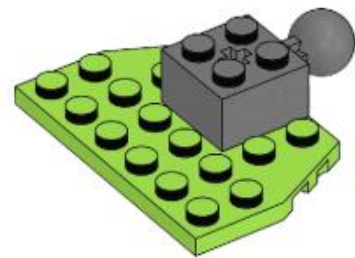
Este capítulo se puede realizar con un kit.

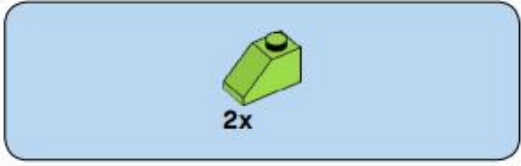


**1**

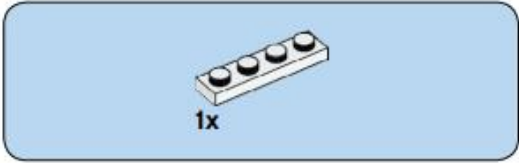
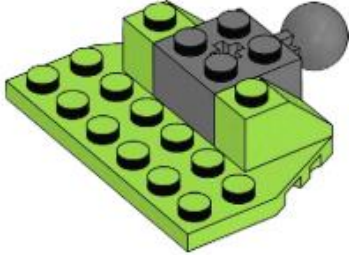


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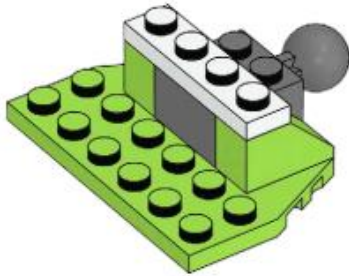


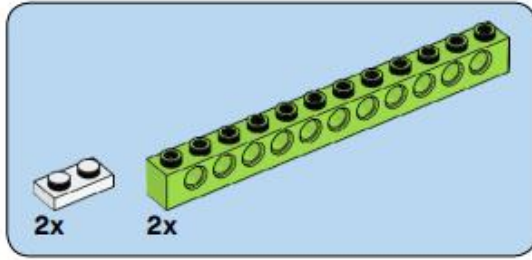


**3**

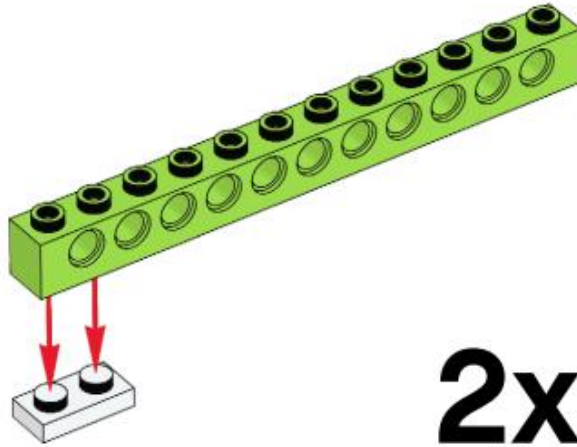


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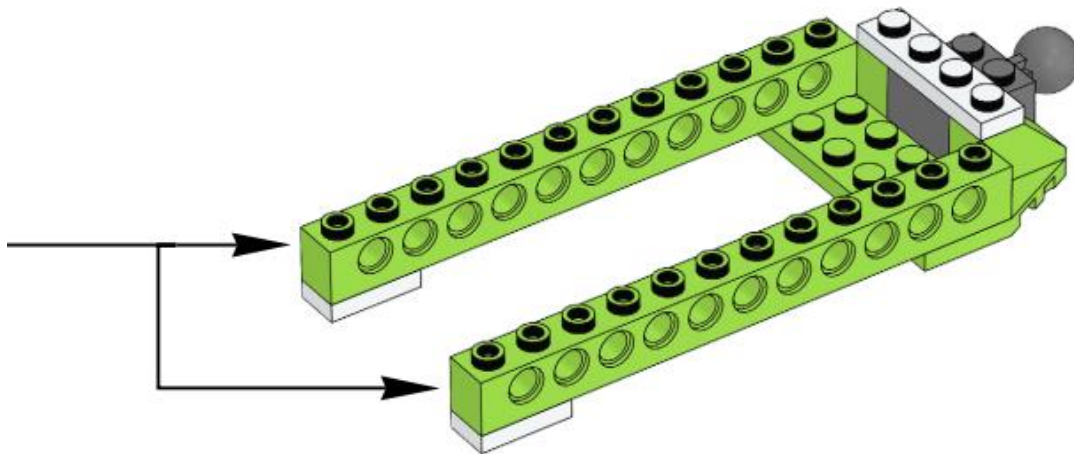


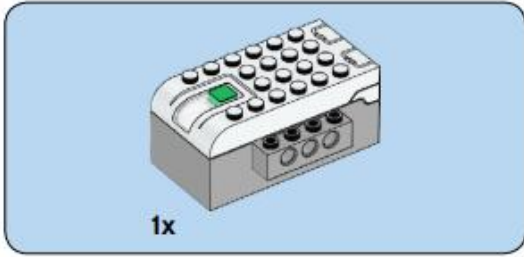


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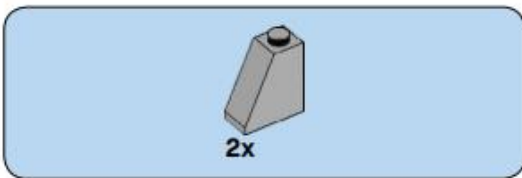
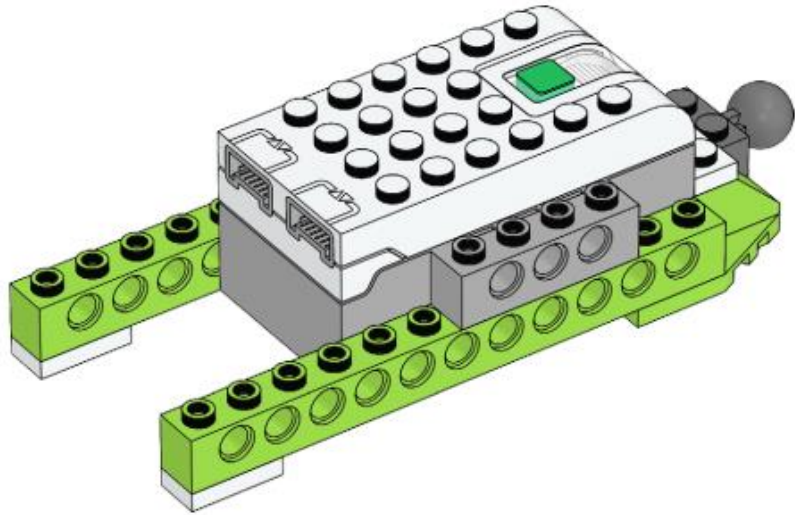


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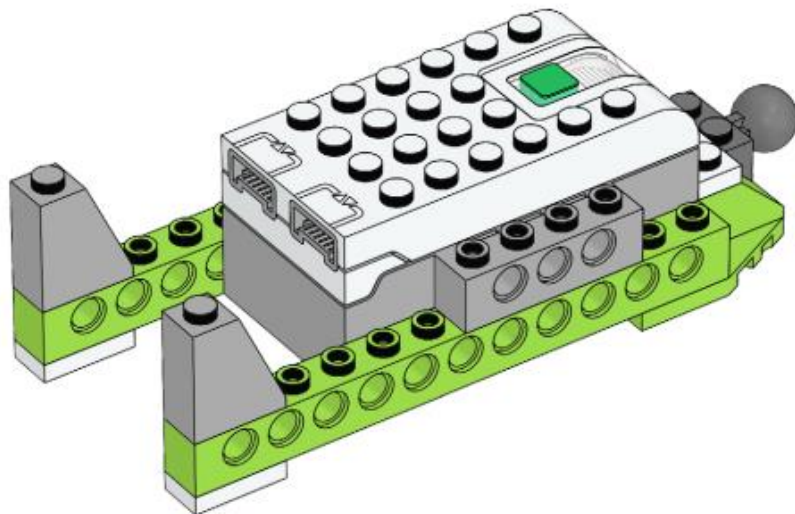


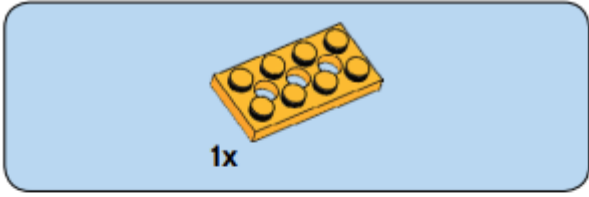


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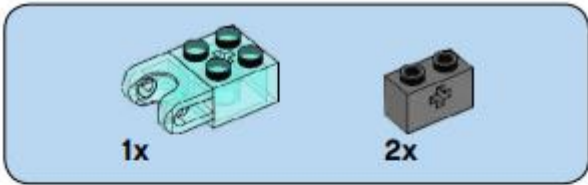
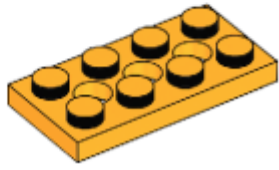


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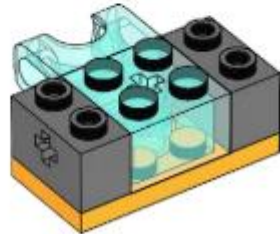


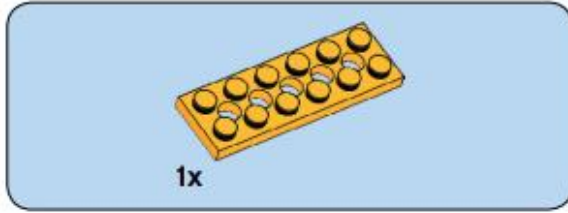


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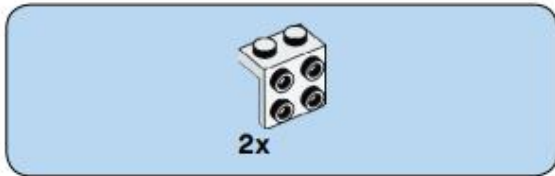
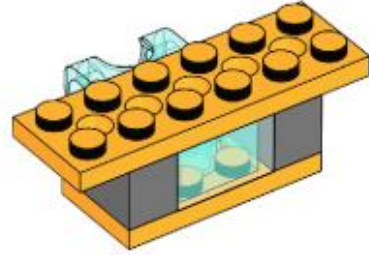


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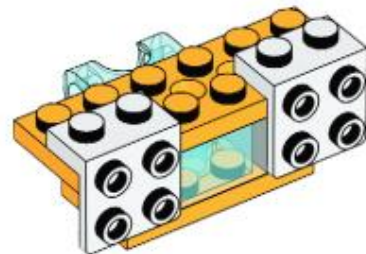




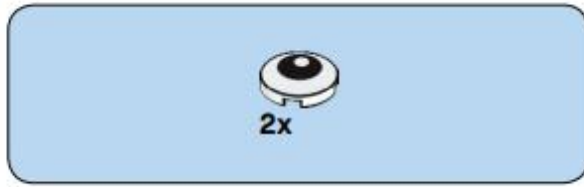
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12



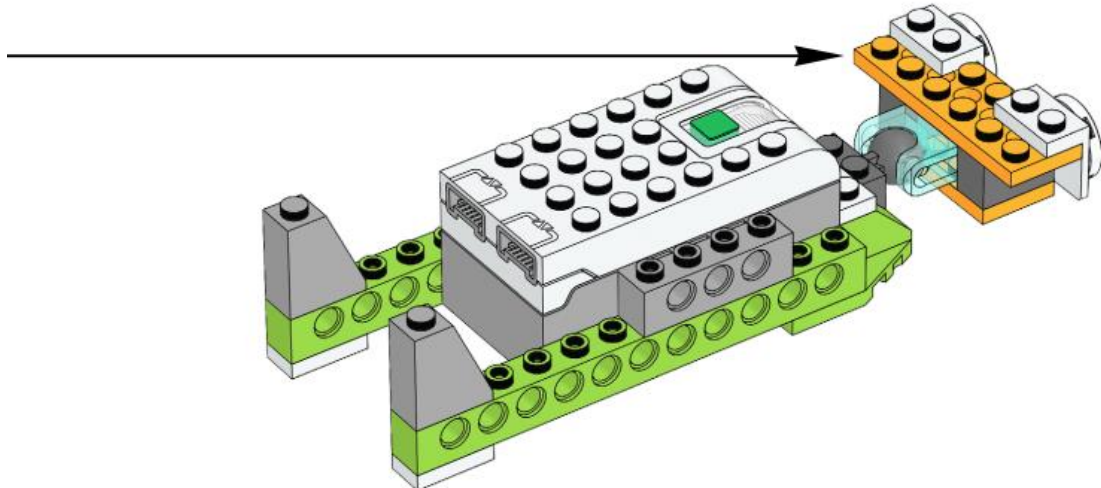




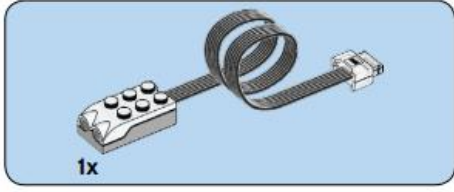
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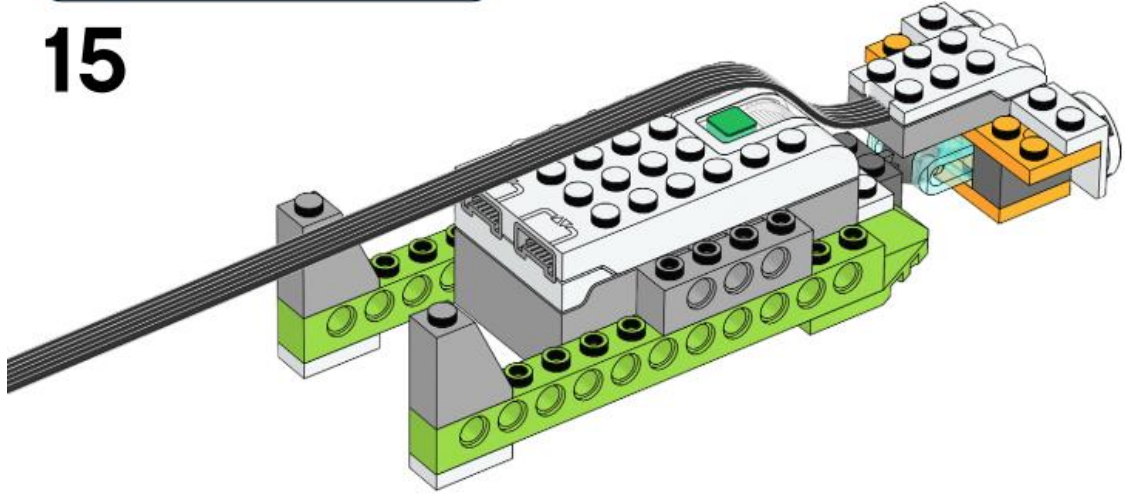
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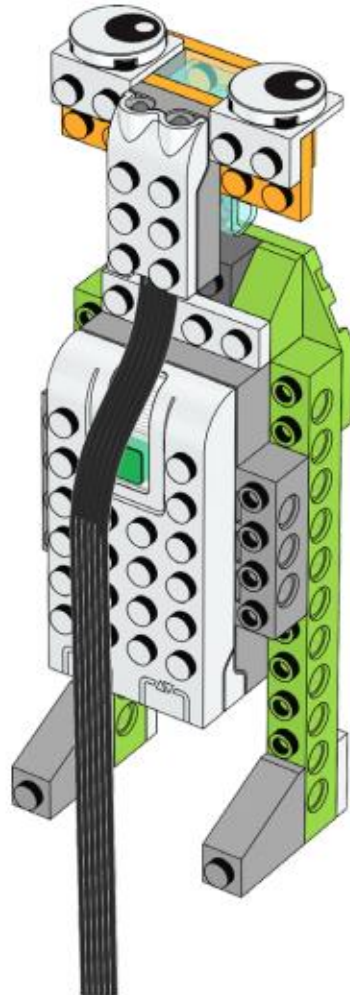




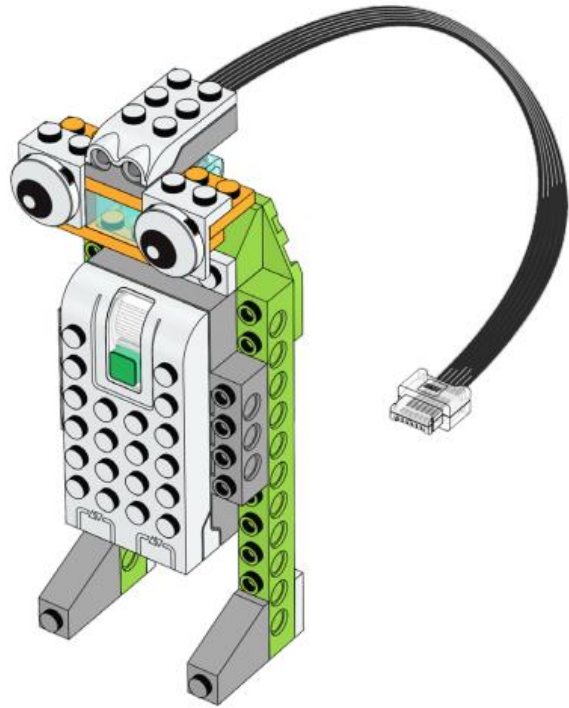
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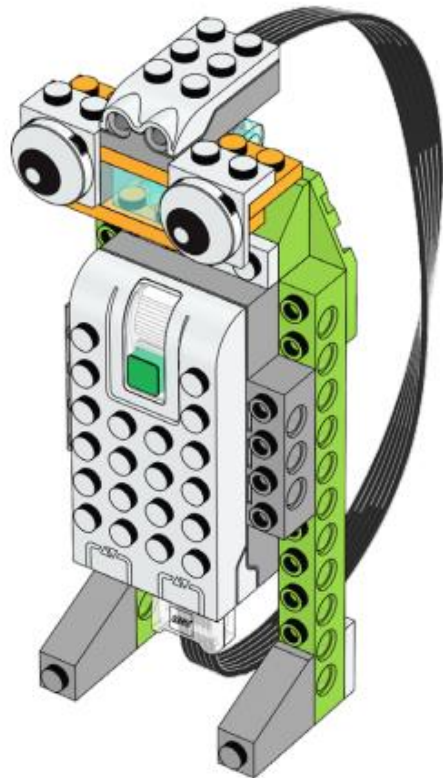
16



17



18



## Codificación

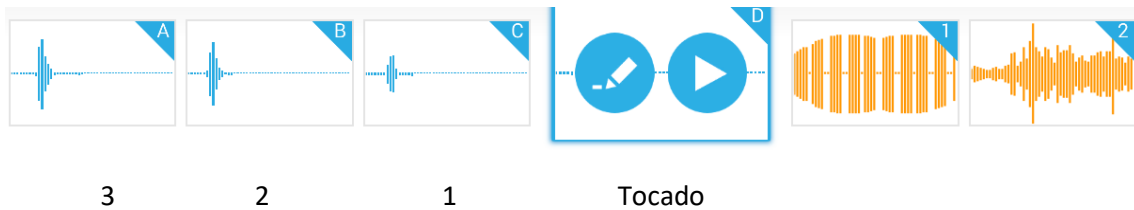
En este capítulo le hemos insertado el detector de objetos, queremos que cuando le aproximemos la mano, nuestro robot realice un sonido.



Para los más avanzados vamos a realizar el correspondiente programa.

Tenemos que grabar 4 mensajes

3, 2, 1 y tocado.



Ahora según tengamos la distancia nos diga el correspondiente mensaje.

